

MLFB-Ordering data

6SL3210-1KE21-7AP1

Item no.: Consignment no. :

Project:



Client order no. :	
Order no. :	
Offer no. :	
Remarks:	

Rated data		
Input		
Number of phases	3 AC	
Line voltage	380 480 V +10 % -20 %	
Line frequency	47 63 Hz	
Rated current (LO)	21.50 A	
Rated current (HO)	18.20 A	
Output		
Number of phases	3 AC	
Rated voltage	400 V	
Rated power IEC 400V (LO)	7.50 kW	
Rated power NEC 480V (LO)	10.00 hp	
Rated power IEC 400V (HO)	5.50 kW	
Rated power NEC 480V (HO)	7.50 hp	
Rated current (IN)	17.00 A	
Rated current (LO)	16.50 A	
Rated current (HO)	12.50 A	
Max. output current	25.00 A	
Pulse frequency	4 kHz	
Output frequency for vector control	0 240 Hz	
Output frequency for V/f control	0 550 Hz	

Overload capability

Low Overload (LO)

150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time

High Overload (HO)

200 % base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time

General tech. specifications			
D (0.70 0.05		
Power factor λ	0.70 0.85		
Offset factor cos φ	0.95		
Efficiency η	0.97		
Sound pressure level (1m)	63 dB		
Power loss	0.24 kW		
Filter class (integrated)	Class A		

Ambient conditions				
Cooling	Air cooling using an integrated fan			
Cooling air requirement	0.009 m³/s (0.318 ft³/s)			
Installation altitude	1000 m (3280.84 ft)			
Ambient temperature				
Operation	-10 40 °C (14 104 °F)			
Transport	-40 70 °C (-40 158 °F)			
Storage	-40 70 °C (-40 158 °F)			
Relative humidity				

95 % At 40 °C (104 °F), condensation Max. operation and icing not permissible

Closed-loop control techniques			
V/f linear / square-law / parameterizable	Yes		
V/f with flux current control (FCC)	Yes		
V/f ECO linear / square-law	Yes		
Sensorless vector control	Yes		
Vector control, with sensor	No		
Encoderless torque control	No		
Torque control, with encoder	No		



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Mechanical	data		Com	
Degree of protection	IP20 / UL open type		Communication	
Size	FSB		Connections	
Net weight	2.30 kg (5.07 lb)		Signal cable	
Width	100 mm (3.94 in)		Conductor cross-section	
Height	196 mm (7.72 in)	Lin	e side	
Depth	203 mm (7.99 in)	Versio	n	
Inputs / out	tputs	Conductor	cross-section	
andard digital inputs		Motor end		
Number	6	Version		
Switching level: 0→1	11 V	Conductor cross-sec	ction	
Switching level: 1→0	5 V	DC link (for braking	resistor)	
Max. inrush current	15 mA	Version		
ail-safe digital inputs		Conductor cross-sect	tion	
Number	1	Line length, max.		
Digital outputs		PE connection		
Number as relay changeover contact	1	Max. motor cable len	gth	
Output (resistive load)	DC 30 V, 0.5 A	Shielded		
Number as transistor	1	Unshielded		
Output (resistive load)	DC 30 V, 0.5 A		St	
Analog / digital inputs		Compliance with stand		
Number	1 (Differential input)	Compliance with stand	iarus	
Resolution	10 bit	CE marking		
Switching threshold as digital in	out			
0→1	4 V			

Number

Analog outputs

1 → 0

1 (Non-isolated output)

PTC/ KTY interface

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy $\pm 5~^\circ\text{C}$

1.6 V



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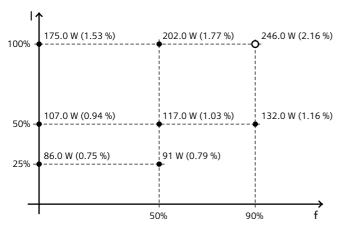
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Figure similar

Converter losses to EN 50598-2*

Efficiency class	IE2
Comparison with the reference converter (90% / 100%)	-63.01 %



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard EN 50598) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

*converted values